DIN-rail mounting temperature controller with current transformer input D1 line

Quick Guide • QG D1 - 1/11.09 • Cod. J30-478-1AD1 QG

CE



via Indipendenza 56, 27029 - Vigevano (PV) Tel.: +39 0381 698 71, Fax: +39 0381 698 730 www.ascontecnologic.com internet site: sales@ascontecnologic.com E-mail:

Configuration and setting Software

The instrument must be configured using **Controller Explorer** (a propietary free software). The most recent release of Controller Explorer is downloadable from our web site:

www.ascontecnologic.com

- To download the file access click on the banner: ascon Select: Download/Software
- Note: The first time you access the Download/Software area, you are requested to register yourself to the site. Press the "Register" key and follow the instructions displayed.

Search and download the file.

Ascon_SW_CE_Xnn.zip (Xnn identifies the release). The default communications parameters are: transmission speed: 9600 bps; protocol: ModBus; serial address: 247

Warning! When more controllers/instruments are to be installed, keep in mind that the default serial address always is 247. For this reason, always connect/power on only 1 not configured instru-ment a time, in order to avoid the presence, on the same network, of 2 instruments with the same address. During the configuration, assign to each instrument a different serial address.

The "gammadue® and deltadue® controller series Serial communications and configuration software" manual can be downloaded from the web site:

www.ascontecnologic.com (then click on: ascon) Select: Download/Documentation, and fill the table with: Manual

- Typology: Type: A11
- Language: All
- Code: SERG2D2
- Click: **SEARCH** and download the file:

Ascon_MIU_SERIALE GAMMA2-DELTA2_RevXX_EN.zip (XX identifies the revision number)

Model code

The product code indicates the specific hardware coniguration of the instrument, that can be modified by specialized engineers only.

Configuration Line Basic Accessories 1st part 2nd par Model: D 1 5 B 5 D - E 9 0 0 / I L M N - O P Q R

Line D	1
Output OP1 - OP2	B
Relay – Not fitted	0
Relay - Relay	1
SSR - Not fitted	3
SSR - SSR	5
Options	D
Options None	D 0
•	
None	0
None Current transformer (CT)	0

Configuration code

A 4 + 4 digits index code follows the model (letters from I... R). This code can be used to buy a pre-configured controller

Input type and range			I	L
TR Pt100 IEC751	-99.9300.0°C	-99.9572.0°F	0	0
TR Pt100 IEC751	-200600°C	-3281112°F	0	1
TC L Fe-Const DIN43710	0600°C	321112°F	0	2
TCJ Fe-Cu45% Ni IEC584	0600°C	321112°F	0	3
TC T Cu-CuNi	-200400°C	-328752°F	0	4
TC K Chromel-Alumel IEC584	01200°C	322192°F	0	5
TC S Pt10%Rh-Pt IEC584	01600°C	322912°F	0	6
TC R Pt13%Rh-Pt IEC584	01600°C	322912°F	0	7
TC B Pt30%Rh Pt6%Rh IEC584	01800°C	323272°F	0	8
TC N Nichrosil-Nisil IEC584	01200°C	322192°F	0	9
TC E Ni10%Cr-CuNi IEC584	0600°C	321112°F	1	0
TC NI-NiMo18%	01100°C	322012°F	1	1
TC W3%Re-W25%Re	02000°C	323632°F	1	2
TC W5%Re-W26%Re	02000°C	323632°F	1	3
Dc input 050mV linear	Engineering units			4
Dc input 1050mVlinear	Engineering units			5
Custom input range [1]				6

Declaration of conformity and manual retrival

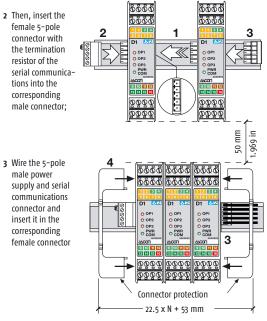
Class II instrument, rear panel mounting. This controller has been designed with compliance to the European Directives. Consult Declaration of Conformity for further details on Directives and Standards used for Compliance. Declaration of Conformity can

be found in the file ASCON_DC_D2.zip. All information about the controller are inserted in the manuals (ASCON_MI_D1_EN.zip and ASCON_MU_D1_EN.zip). The Declaration of Conformity and the manuals of the controller can be downloaded (free of charge) from the web-site: www.ascontecnologic.com Once connected to the web-site, click on the **ascon** logo. Select: Download/Documentation, and fill the table with: • Typology: Manual; Type: All; Language: All; Code: DELTA2 Click: SEARCH and • Download the file: ASCON_DC_D2.zip (Declaration of

- Conformity of delta2 controllers) ASCON_MI_D1_EN.zip (Installation) ASCON_MU_D1_EN.zip (User) or
- **△** Warning!
- Whenever a failure or a malfunction of the device may cause dangerous situations for persons, things or animals, please remember that the plant must be equipped with additional devices which will guarantee safety. - We warrant that the products will be free from defects in material and
- workmanship for 18 months from the date of delivery. Products and components that are subject to wear due to conditions of use, service life, and misuse are not covered by this warranty.

Mounting several instruments

1 Mounted the instruments on the rail, put them side by side so that the male side connector fits into the corresponding female connector



4 When assembled insert the connector protection on both sides.

Dimensions 99 mm 3.9 in 114.5 mm 4.5 in 88888

D D D D D D

Plug with termination

communications bus

resistor for serial

13 14

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Features

Stripped

Flat blade

screwdrive

wire

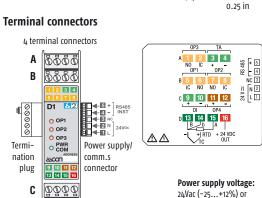
TTL

m٧

Terminals

(male)

Connections



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OP4

External

Shunt 2.5 Ω

- + ²⁴ 13 14 15

N0⁷

Current

transformer

Connector for

24VDC

A - B - C - D

= 7 mm - 0.28 in

0.6 x 3.5 mm

0.5... 0.6 Nm

13 14

`mA

power supply and

serial communica-

tions bus (female)

Power supply voltage: 24Vac (-25...+12%) or 24Vdc (-15....+25%)

Configuration

RS485

and Supervision

24V

Pt100

Power

supply

switch

13 14 15

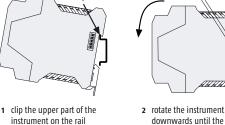
BDA

Bus/Power Supply

L = 7 mm - 0.28 in

0.4 x 2.5 mm

0.4... 0.5 Nm

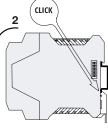


DIN rail mounting

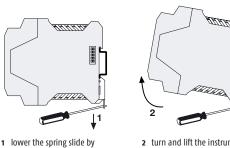
22.5 mm

0.89 in

6.3 mm



downwards until the click Removing the instrument from the DIN rail

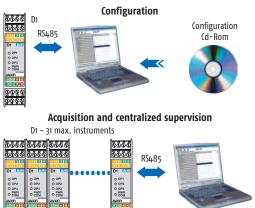


inserting a flat-blade screwdriver as indicated

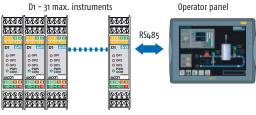
Switch off the instrument

2 turn and lift the instrument upwards.

Serial communications connection examples



Local control



Parameters list

⊢∟⊣

In the table that follows are listed the parameters of the controller associated to the correspondent serial ModBus address. For further details, consult the manual: "gammadue® and deltadue® controller series Serial communications and configuration software".

Control mode					М		
ON-OFF reverse action						0	
ON-OFF direct action						1	
PID single reverse action					2		
PID single direct action	n						3
		Linear cool ou	tput				4
PID double action		ON-OFF cool o	utput				5
		Water cool out	put				6
		Oil cool output	t				7
						- 1	
Single Action	Output configuration Single Action Double action					Ν	
<u> </u>							
Relays (OP1)		Heat OP1, Cool OP2					0
SSR drive (OP4)		Heat OP1, Cool OP4					1
55/(01172 (014)		Heat OP4, Cool OP2					2
					0	Ρ	Q
Tipo e modo di inte	ervento alla	mi			-	-	
N. 11 1	r () (41-1		AL.	1	2	3
Disabled or used by Timer (only for AL3)			0	0	0		
Sensor break/Loop Break Alarm (LBA)			1	1	1		
Absolute active active		0			2	2	2
		low			3	3	3
Deviation	high			4	4	4	
Deviation	viation						-

Tightening 1 torque

Analogue

ModBus	Parameter name		Value			
address	Parameter name	Default	Modbus	User		
0	PV process variable					
1	SP Setpoint					
2	Main output					
3	SPT Target Setpoint					
4	SPL local Setpoint					
5	Proportional band (PID) or Hysteresis (ON – OFF)	5.0 or 0.5	50 or 5			
6	Overshoot control	1.00	100			
7	Integral time	5.0	50			
8	Derivative time	1.00	100			
9	Control output cycle time (heat)	20	20			
10	Low range					
11	High range					
12	AL2 alarm threshold	0	0			
13	AL3 alarm threshold	0	0			
14	AL2 alarm hysteresis	0.5	5			
15	AL3 alarm hysteresis	0.5	5			
16	Relative Cold Gain	1.0	10			

ModBus	Deremeter		Value		
address	Parameter name	Default Modbus Use			
-0	Start/Stop One shot tuning	-4			
38	(o = stop, 1 = start)	stop	0		
39	Overshoot Control relative band	0.5	5.0		
44	Start-up Setpoint	0	0		
45	Start–Up Hold time	1	1		
46	Output high limit during Start-up	100.0	1000		
47	Timer remaining time	0.5	5		
49	Setpoint selection	local	0		
50	1 st stored Setpoint				
51	2 nd stored Setpoint				
56	AL1 alarm threshold	0	0		
57	AL1 alarm hysteresis	0.5	5		
58	AL1 latching and blocking	none	0		
59	AL2 latching and blocking	none	0		
60	AL3 latching and blocking	none	0		
61	LBA delay	inhibited	0		
62	Instrument position	single	0		
02	Read the first 16 coils on word	Single	0		
63	(B.O.R. = Bit On Register)				
)igital ModBus	Parameter		Value		
address					
1	Automatic/Manual	o = Automat		ual	
2	OP4 logical output status	0 = 0FF, 1 =			
3	OP1 digital output status	0 = 0FF, 1 =			
4	OP2 digital output status	0 = 0FF, 1 =			
5	OP3 digital output status	0 = 0FF, 1 =			
6	Out of range status	o = Normal o 1 = Safety			
7	Auto-Tune status	o = Disabled	, 1 = Run		
8	Timer function status (if option present)	0 = 0FF, 1 = Run			
	Forcing the Output status	o = Not influenced, 1 = Forced to OFF			
11	- ·		0 = 0FF, 1 = 0N		
12	IL Digital Input status				
	- ·	0 = 0FF, 1 = 1 = Tune fail			

	active low		5	5	5
Band	active out		6	6	6
banu	active in		7	7	7
Setpoint type					R
Local only					0
Local and 2 tracking stored Setpoint					1
Local and 2 Stand-by stored Setpoint					
	e, other thermocouples types, earisation etc.	∆T (wit	h 2 P	T100)),
[2] 2 different correcting methods of the control output are av					

ble. One for water and the other for oil:

OP water=100•(0P2/100)² - 0P oil=100•(0P2/100)^{1.5}

					<i>c</i> -	meaa cin	
17	Cool output Hysteresis (ON-OFF)	0.5	5		63	(B.O.R. :	
19	Heat/Cool Dead band	0.5	5		Digital		
20	Cool cycle time	20	20				
21	Cool output maximum value	100.0	1000		ModBus address		
24	Timer setting	0.5	5		1	Automat	
25	Timer Stand-by Setpoint	0	0		2	0P4 logi	
26	Soft-start output value	0.5	5		3	0P1 digit	
27	Soft-start activation time	1	1		4	OP2 digi	
28	Manual reset	50.0	500		5	OP3 digi	
29	Setpoint low limit	low range			6	Out of ra	
30	Setpoint high limit	high range			7	Auto-Tu	
31	Error Dead Band	inhibited	0		-	Timer fu	
32	Control output high limit	100.0	1000		8	(if optio	
33	Output safety value	0.0	0		11	Forcing t	
34	Slope up	inhibited	0				
35	Slope down	inhibited	0		12	IL Digita	
		inhibited			13	Tune Fai	
36	Input filter	minubiled	0		15	Latching	
37	Input shift	inhibited	0		0	acknow	